

starcopter

THE HIGHDRA
SYSTEM OVERVIEW





1

System Overview



2

Descriptions of Components



According to the **HIGHDRA** Operating Manual v1.1

System Overview



2.1 DELIVERY SCOPE

| Items | Quantity |
|---|----------|
| Aircraft Body | 1 |
| Arm, incl. Propeller | 6 |
| Propeller Transport Safeguards | 6 |
| Landing Leg Vertical Part | 2 |
| Landing Leg Horizontal Part | 2 |
| Remote Control (RC) | 1 |
| Remote Control Charging Cable (Micro USB) | 1 |
| Powerbank (for the Remote Control) | 1 |
| Battery Set (6 individual batteries) | 1 |
| Battery Charging Station | 1 |
| EASA Information Notice | 1 |

2.2 SPECIFICATIONS

| Items | Unit (g) | Quantity | Subtotal (g) |
|----------------------|----------|----------|---------------|
| Body | 3,700 | 1 | 3,700 |
| Arm, incl. Propeller | 750 | 6 | 4,500 |
| Landing Leg | 300 | 2 | 600 |
| Battery | 1,450 | 6 | 8,700 |
| Total | | | 17,500 |



Remote, Control
(RC)



Battery, Charging
Station



Arm, including
Propeller



In-house Battery Set:
6 individual batteries



Aircraft Body

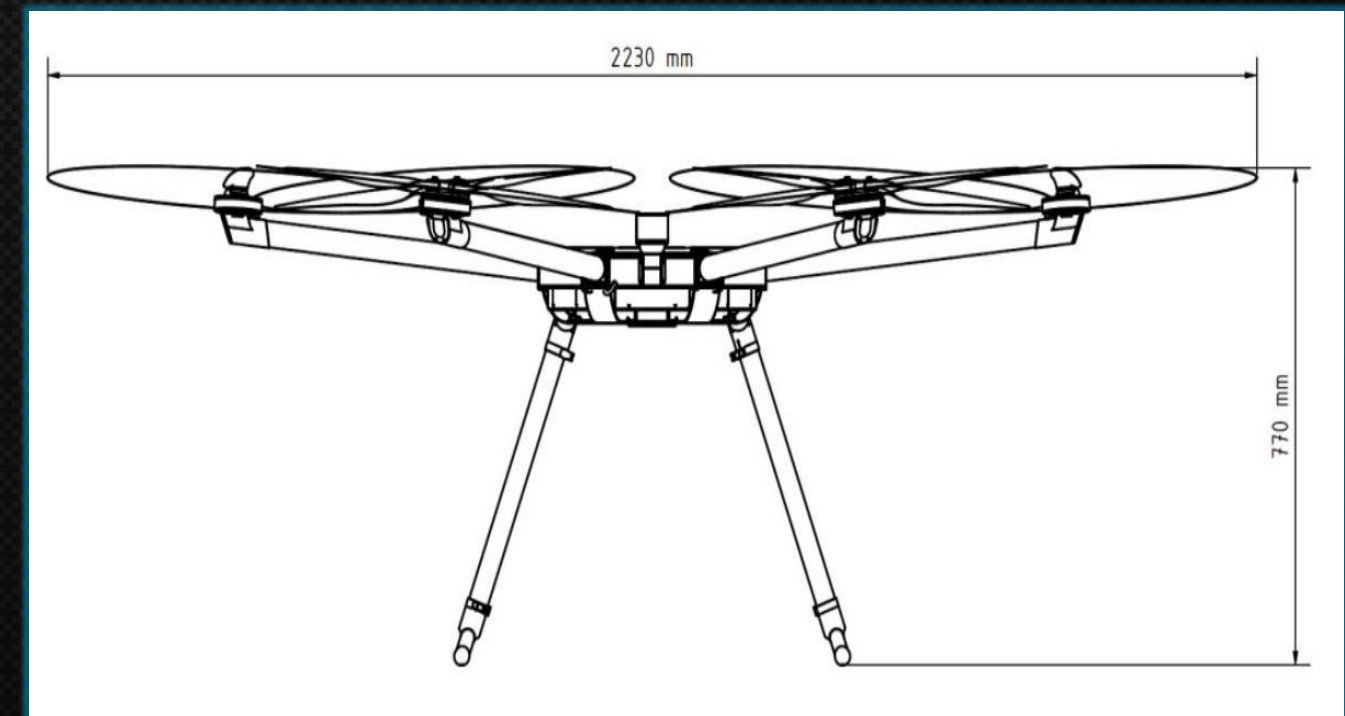
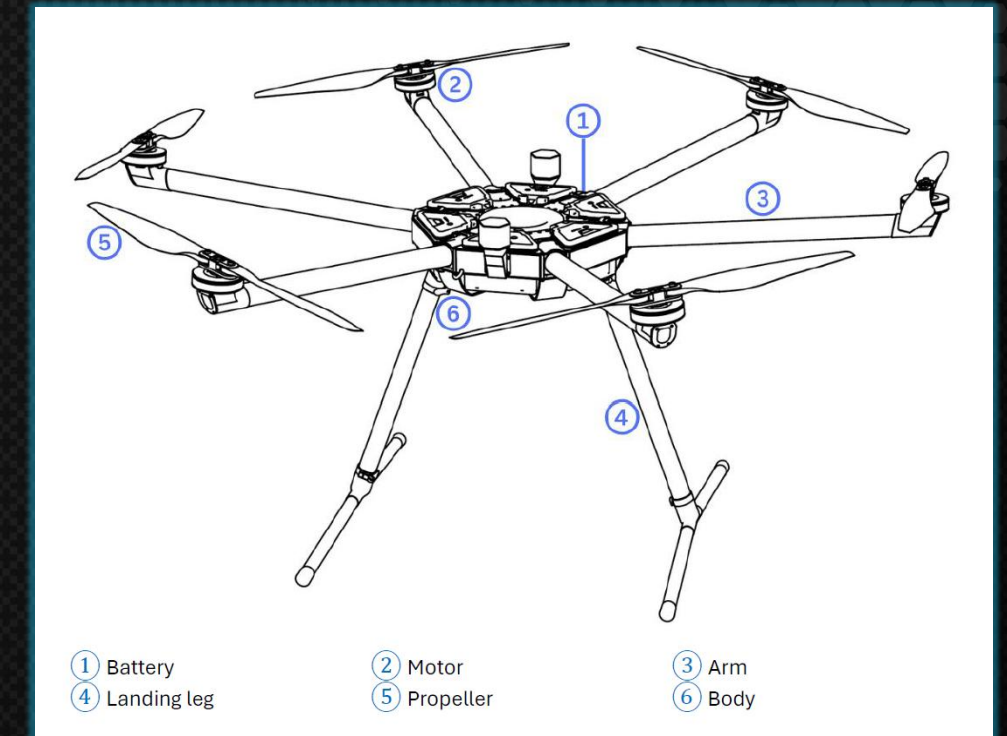


Landing Leg:
Horizontal and
Vertical Part

Description of Components



- ✓ **Battery**
- ✓ **Motor**
- ✓ **Arm**
- ✓ **Landing Leg**
- ✓ **Propeller**
- ✓ **Body**





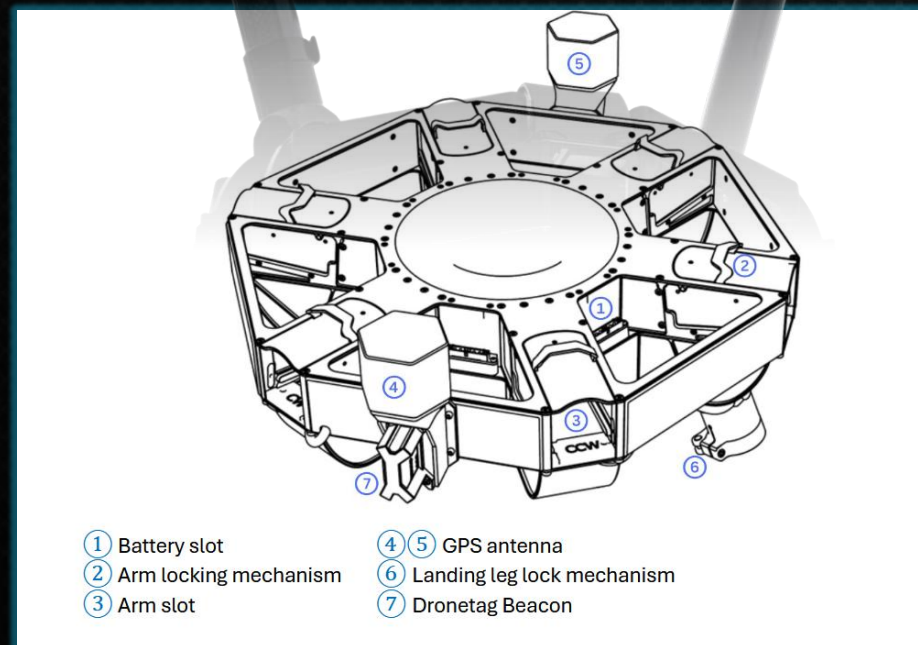
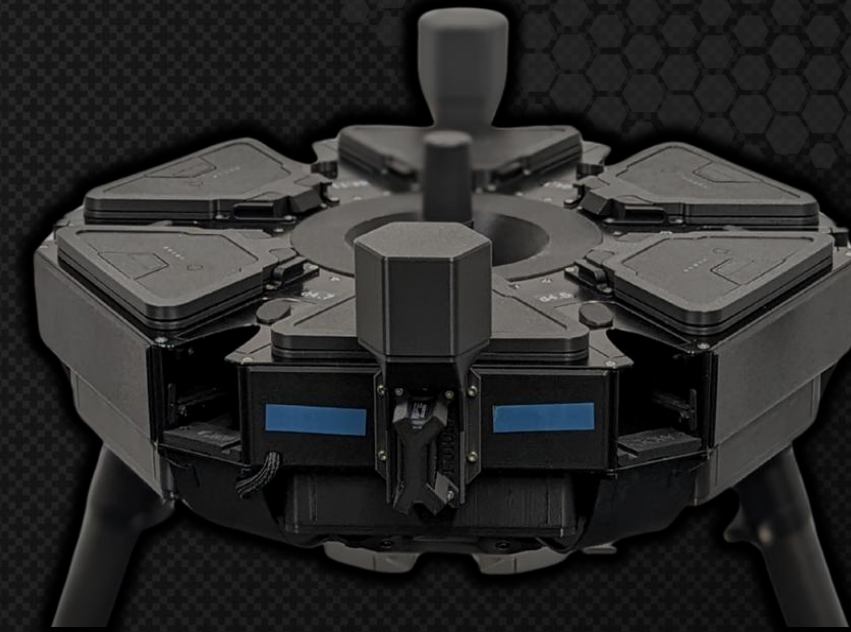
Body



A.I. ready body
Powered by Auterion



Compatible with various
sensors for different
missions



HIGHDRA

| | |
|-------------------------------------|--|
| UAS Class | C3 |
| Operating Area in the Open Category | A3 |
| Max. Takeoff Mass | 24.99 kg |
| Dimensions | 223.0 (W) x 202.6 (D) x 77.0 (H) cm |
| Max. Flight Time | 60 min without payload 30 min, with max. Takeoff Mass |
| Max. Tilt Angle | 36° |
| GNSS | GPS, GLONASS, Galileo and BDS |
| Hovering Accuracy Range | Vertical: ±20 cm (with GPS position) Horizontal: ±30 cm (with GPS position) |
| Guaranteed Sound Power Level | 104 dBA |
| Max. Altitude (AMSL) | 3500m with up to 2.5 kg Payload 1500 m with MTOM |
| Altitude Line of Sight | 749 m |



Arm, Propeller and Landing Leg

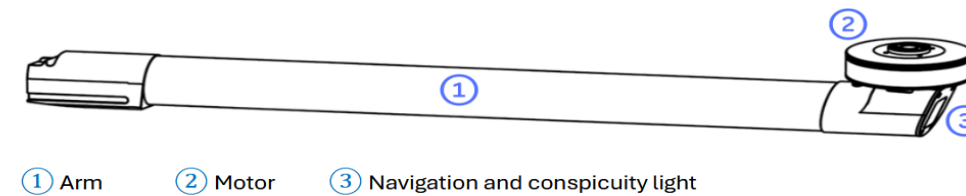
Modular
legs & arms



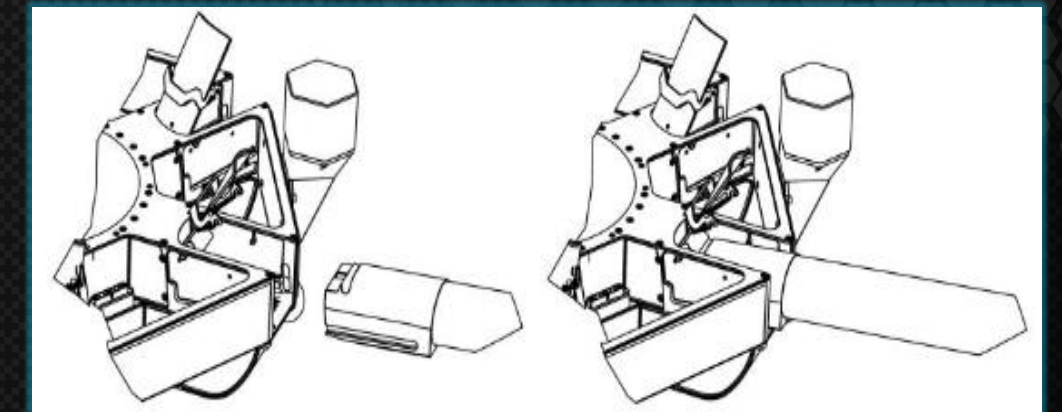
2.3.2 Arm

The arm is constructed from a combination of aluminum and carbon-fiber tubing. It incorporates an integrated brushless AC motor and a navigation light system. The color of the navigation light corresponds to the arm's position on the UAV body and changes sequentially.

The navigation and conspicuity light patterns are outlined in 2.3.2.1 Navigation and Conspicuity Lights.



Aluminium and
Carbon-fiber
tubing



Quick-Locking
Mechanism



2.3.3 Propeller

The UAV uses 28-inch Mejzlik propellers made of carbon fiber, which have been factory balanced for optimal performance. The drone is equipped with six foldable propellers in total: three rotate clockwise (CW) and three rotate counterclockwise (CCW)



Mejzlik
carbon fiber
propellers

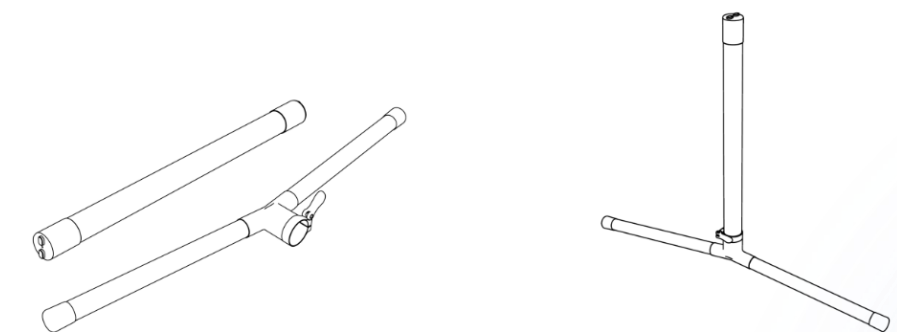


Quick-Release
Mechanism



2.3.4 Landing Leg horizontal and vertical part

The starcopter HIGHDRA is equipped with two landing legs, each of which can be detached using a quick-release mechanism for easy removal and replacement.





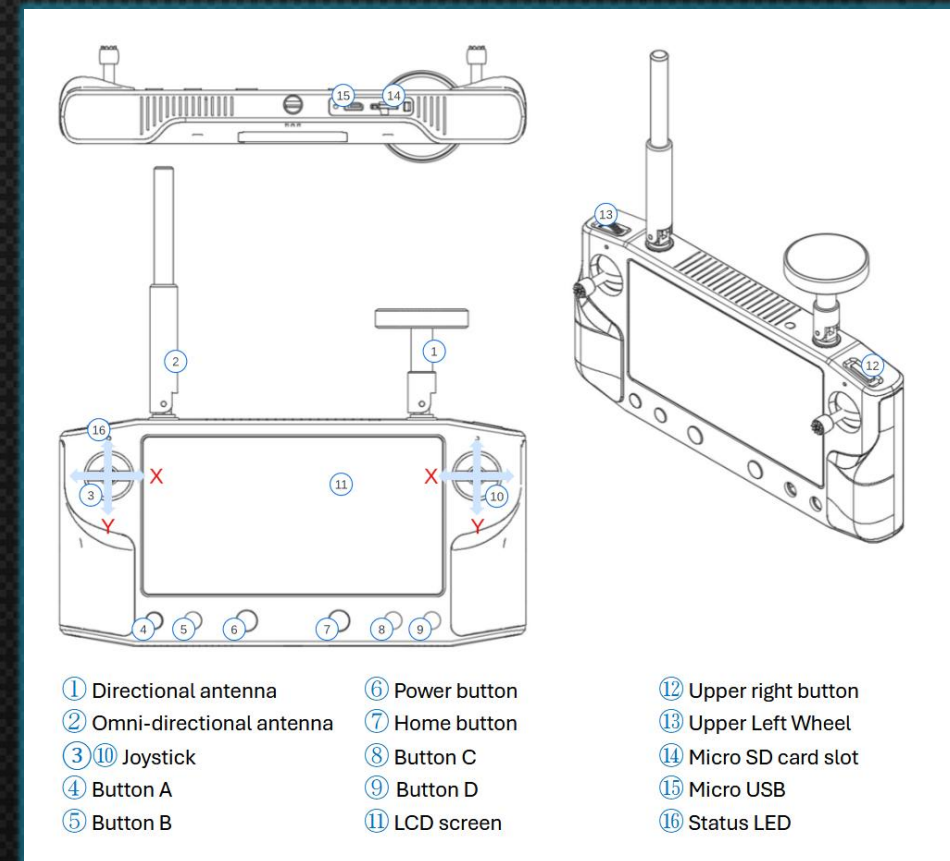
Remote Control (RC)



CubePilot
Remote Control



Pre-installed
Auterion Mission
Control




Do not perform any software updates on the remote control yourself.

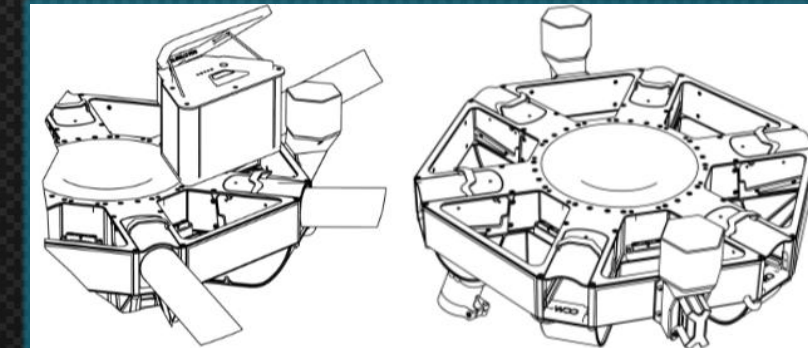
| Left Stick | | Right Stick | |
|----------------------|--------------------------|---------------------------------|----------------------------|
| | Altitude (speed) Up | | Forward (speed) Forward |
| | Down | | Back |
| | Turn (rate) Turn Left | | Left/Right (speed) Left |
| | Turn Right | | Right |
| Button/Joystick | | Description | |
| ③ Stick (left) | | X-axis: Yaw Y-axis: Throttle | |
| ⑩ Stick (right) | | X-axis: Roll Y-axis: Pitch | |
| ④ Button A | | Position Mode | |
| ⑤ Button B | | Altitude Mode | |
| ⑥ Power button | | Turn on/off the RC | |
| ⑦ Home button | | Return to Launch (RTL) | |
| ⑧ Button C | | Kill | |
| ⑨ Button D | | No function | |
| ⑫ Upper right button | | No function | |
| ⑬ Upper Left Wheel | | No function | |



Battery



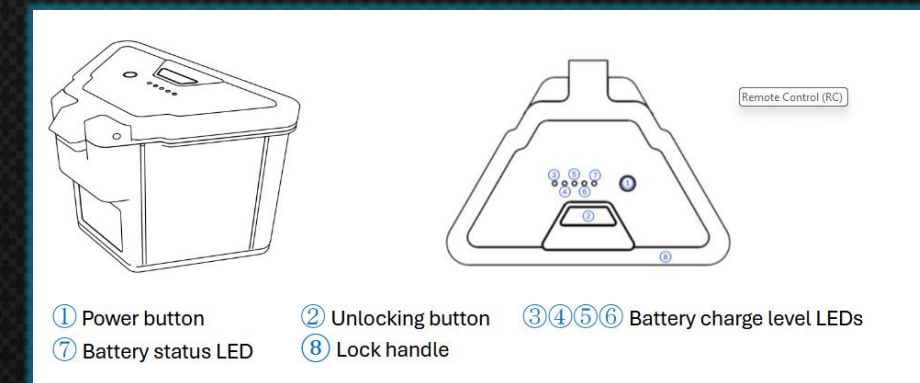
A set of Six
independent 24 V 
Highdra Power
Packs




starCopter
HIGHDRA® Power Pack
Rechargeable Lithium Ion Battery
21.6 V 12.6 Ah 272 Wh
MFG: XXXX-XX-XX
SN: XXXX XXXX Set-ID: XXX



Internally
managed by 
Highdra BMS
circuitry and
software



| Battery | |
|----------------------------------|------------|
| Battery Capacity | 272 Wh |
| Voltage | 24.0 VDC |
| Charging Voltage Limit | 25.2 VDC |
| Battery Type | Li-Ion 6S |
| Weight | 1,450 g |
| Charging Environment Temperature | Max. 40 °C |

 Never mix batteries with different Set-IDs or color-codes.



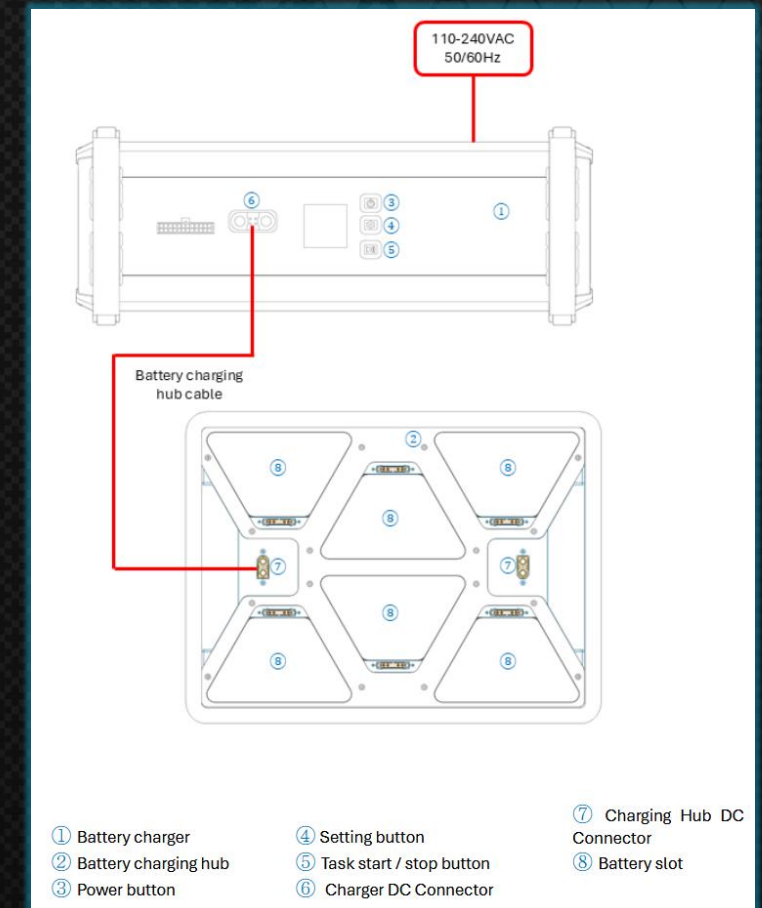
Battery Charging Station



Simultaneous
charging of 6
batteries



Easy Plug and
Charge principle



| Battery Charger | |
|------------------------|------------------------------------|
| Input voltage | 110~240 VAC |
| Output voltage | 20~58 VDC |
| Max. input current | AC 16 A |
| Max. charging power | 3000 W (@220 VAC) |
| Max. discharging power | 200 W |
| Charging current | 1.0~52.0 A (Max) |
| Discharging current | 0.5~5.0 A (Max) |
| Working temperature | 0°C to 40 °C |
| Storage temperature | -20°C to 60 °C |
| Size | 35.6 × 13.68 × 16.41 cm |
| Weight | about 3973 g |
| Charging Duration | Six (6) batteries @ 55 A – 1 hours |

When using the **Fast Charge Mode**, no other devices must be plugged into the same Power Outlet. The maximum power could be exceeded resulting in tripping the fuse.



Payload



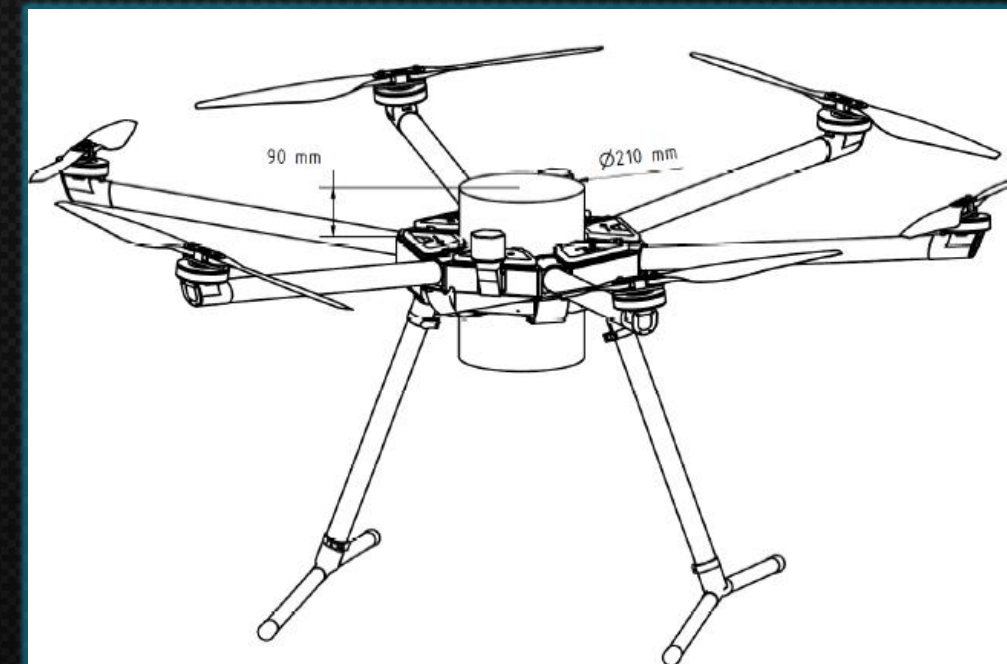
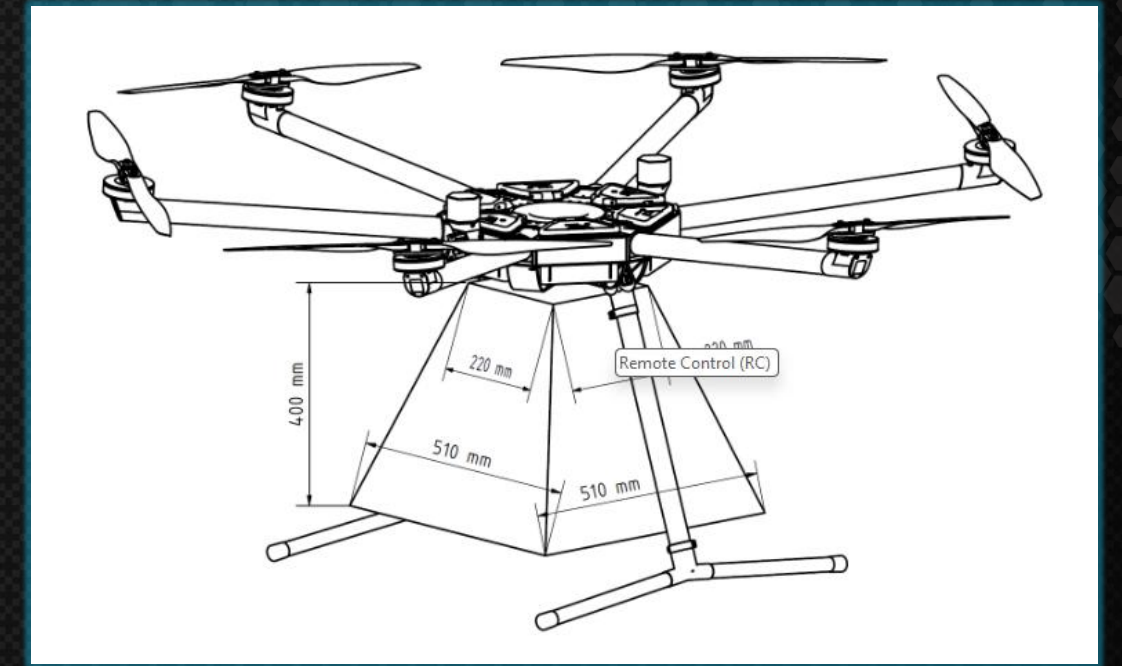
Standalone
payload system
accommodation



Individual request
Integration of
payload system



| Parameter | Value |
|-------------|---------|
| Max. Weight | 7.49 kg |

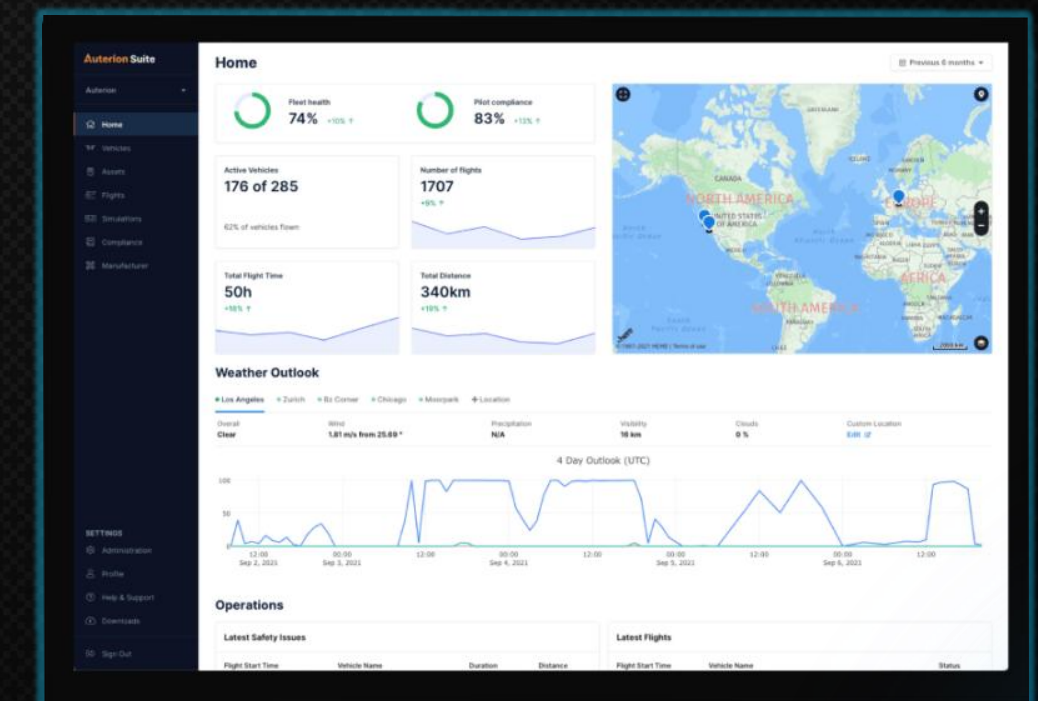


SOFTWARE UPDATES AND UAV UPGRADES



2.4 SOFTWARE UPDATES AND UAV UPGRADES BY STARCOPTER

starcopter will exclusively manage all software updates for you. In case of critical safety updates, starcopter will notify you via email, perform a guided update with you and handle all occurring software update issues.





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The Highdra



starcoputer.com